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// Eye Blink Detection (Experimental!) - BioAmp EXG Pill
// https://github.com/upsidedownlabs/BioAmp-EXG-Pill

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#include <math.h>

#define SAMPLE_RATE 75
#define BAUD_RATE 115200
#define INPUT_PIN A0
#define OUTPUT_PIN 13
#define DATA_LENGTH 10

int data_index = 0;
bool peak = false;

void setup() {
    // Serial connection begin
    Serial.begin(BAUD_RATE);
    // Setup Input & Output pin
    pinMode(INPUT_PIN, INPUT);
    pinMode(OUTPUT_PIN, OUTPUT);
}

void loop() {
    // Calculate elapsed time
    static unsigned long past = 0;
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unsigned long present = micros();
unsigned long interval = present - past;
past = present;

// Run timer
static long timer = 0;
timer -= interval;

// Sample
if(timer < 0){
    timer += 1000000 / SAMPLE_RATE;
// Sample and Nomalize input data (-1 to 1)
    float sensor_value = analogRead(INPUT_PIN);
    float signal = EOGFilter(sensor_value)/512;
// Get peak
    peak = Getpeak(signal);
// Print sensor_value and peak
    Serial.print(signal);
    Serial.print(",");
    Serial.println(peak);
// Blink LED on peak
    digitalWrite(OUTPUT_PIN, peak);
}
}

bool Getpeak(float new_sample) {
    // Buffers for data, mean, and standard deviation
    static float data_buffer[DATA_LENGTH];
    static float mean_buffer[DATA_LENGTH];
    static float standard_deviation_buffer[DATA_LENGTH];

    // Check for peak
    if (new_sample - mean_buffer[data_index] > (DATA_LENGTH*1.2) *
standard_deviation_buffer[data_index]) {
        data_buffer[data_index] = new_sample + data_buffer[data_index];
        peak = true;
    } else {
        data_buffer[data_index] = new_sample;
        peak = false;
    }

    // Calculate mean
    float sum = 0.0, mean, standard_deviation = 0.0;
    for (int i = 0; i < DATA_LENGTH; ++i){
        sum += data_buffer[(data_index + i) % DATA_LENGTH];
    }
    mean = sum/DATA_LENGTH;

    // Calculate standard deviation
    for (int i = 0; i < DATA_LENGTH; ++i){

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        standard_deviation += pow(data_buffer[(i) % DATA_LENGTH] - mean,
2);
    }

    // Update mean buffer
    mean_buffer[data_index] = mean;

    // Update standard deviation buffer
    standard_deviation_buffer[data_index] =
sqrt(standard_deviation/DATA_LENGTH);

    // Update data_index
    data_index = (data_index+1)%DATA_LENGTH;

    // Return peak
    return peak;
}

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// Band-Pass Butterworth IIR digital filter, generated using filter_gen.py.
// Sampling rate: 75.0 Hz, frequency: [0.5, 19.5] Hz.
// Filter is order 4, implemented as second-order sections (biquads).
// Reference:
// https://docs.scipy.org/doc/scipy/reference/generated/scipy.signal.butter.html
// https://courses.ideate.cmu.edu/16-223/f2020/Arduino/FilterDemos/filter\_gen.py
float EOGFilter(float input)
{

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    float output = input;
    {
        static float z1, z2; // filter section state
        float x = output - 0.02977423*z1 - 0.04296318*z2;
        output = 0.09797471*x + 0.19594942*z1 + 0.09797471*z2;
        z2 = z1;
        z1 = x;
    }
    {
        static float z1, z2; // filter section state
        float x = output - 0.08383952*z1 - 0.46067709*z2;
        output = 1.00000000*x + 2.00000000*z1 + 1.00000000*z2;
        z2 = z1;
        z1 = x;
    }
    {
        static float z1, z2; // filter section state
        float x = output - -1.92167271*z1 - 0.92347975*z2;
        output = 1.00000000*x + -2.00000000*z1 + 1.00000000*z2;
        z2 = z1;
        z1 = x;
    }
    {
        static float z1, z2; // filter section state

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float x = output - -1.96758891*z1 - 0.96933514*z2;  
output = 1.00000000*x + -2.00000000*z1 + 1.00000000*z2;  
z2 = z1;  
z1 = x;  
}  
return output;  
}
```